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DijkstraAlgorithm Arbitrarily select node e as the initiaJ frag ment. Arcs are added in the following order: (d,e), (b,d), (b,c) {tie with (a,b) is broken arbitrarily}, (a, b), (a, J). Kruskal's Algorithm Start with each node as a fragment. Arcs are added

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6: Dynamic programming
Chapter 7: Linear programming

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human activities: education, commerce, entertainment, research, manufacturing, health

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6.21 (DPV) Let C(v) be the size of a

minimum vertex cover of the subtree rooted at v. Answer: C(root) Base Case: C(leaf) = 0. Case 1 (v is in the solution) Then the optimal way to extend the partial solution is to take the optimal solution of each child. i.e. 1 + ??:? ??? ?? ?)?(?

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12(x+2). (5 marks) Rearrange the equation to get it in intercept form, or solve y= 0 for x ...

Answers, Solution Outlines and Comments to Exercises Chapter 6 Dynamic programming In the preceding chapters we have seen some

elegant design principlesŠsuch as divide-and-conquer, graph exploration, and greedy choiceŠthat yield denitive algorithms for a variety of important computational tasks. The drawback of these tools is that they can only be used on very specic

types of problems.

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subsequence, and so on. In such cases, we seek a solution that (1) satises certain constraints (for instance, the path must use edges

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Give an O(nt) algorithm for the following task.Input: A ...

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Exercises from Chapter 0;
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Elementary Number
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